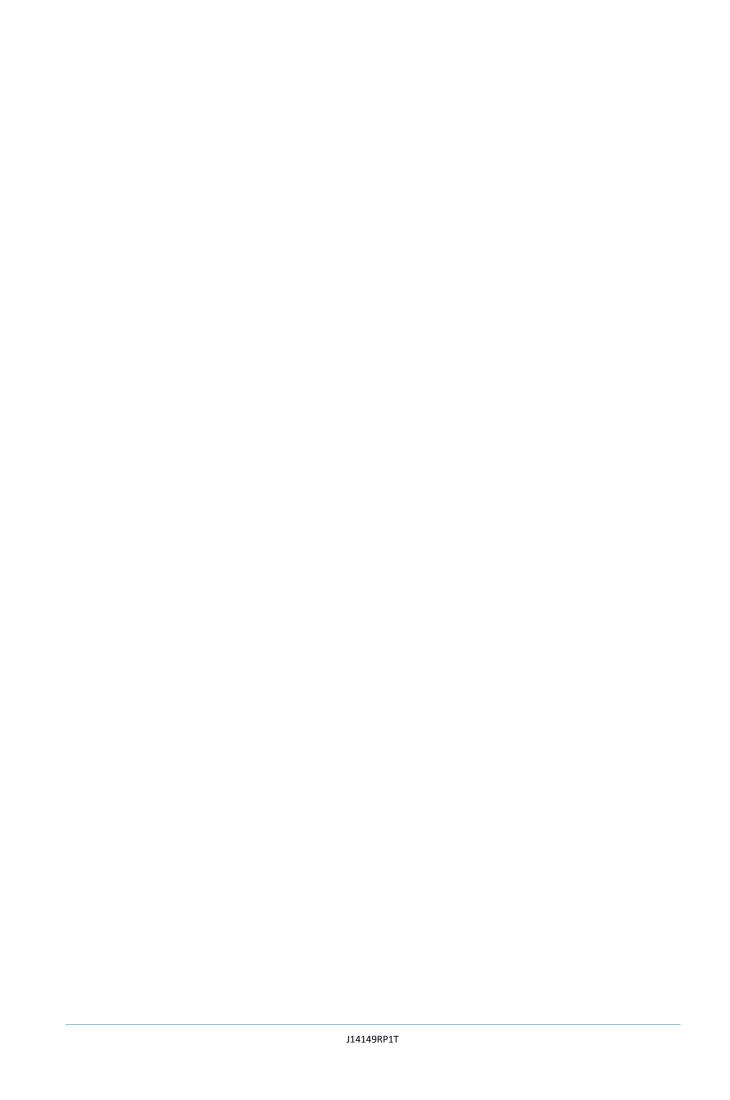
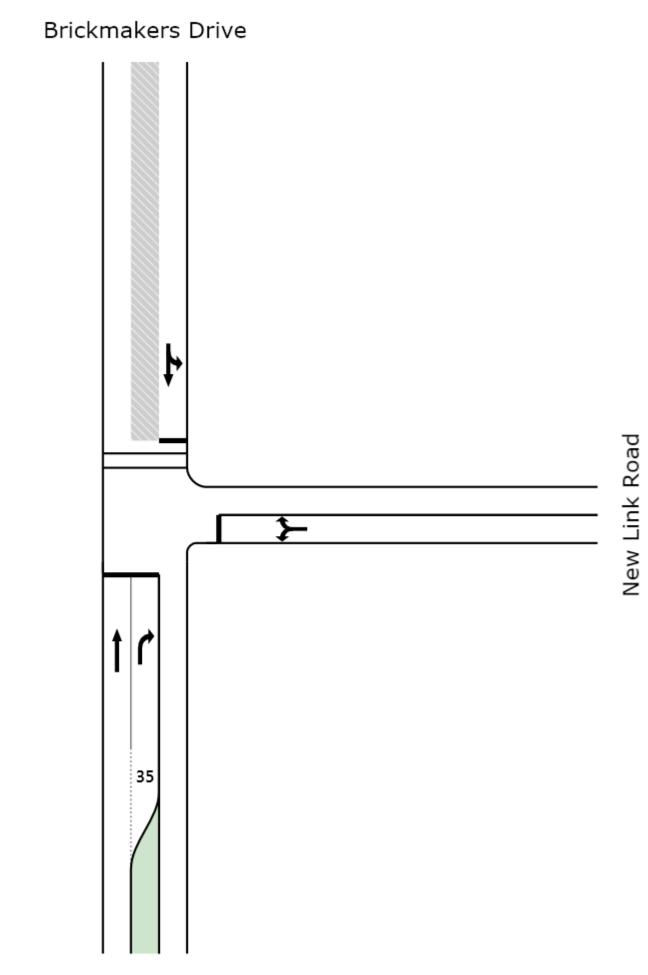


Appendix B										
SIDRA intersection results										





Brickmakers Drive

PHASING SUMMARY

Site: Traffic Signals AM Peak Proposed Development

New T Intersection

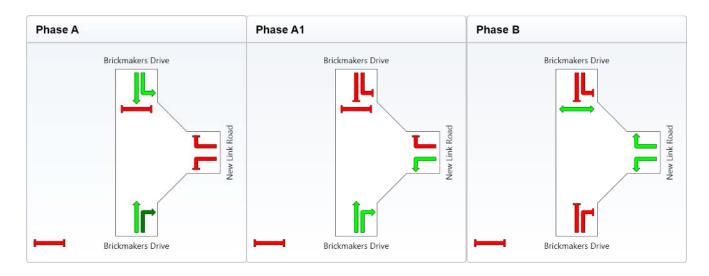
Signals - Fixed Time Cycle Time = 60 seconds (User-Given Cycle Time)

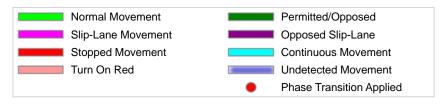
Phase times determined by the program

Sequence: Opposed Turns Input Sequence: A, A1, B Output Sequence: A, A1, B

Phase Timing Results

Phase	Α	A1	В
Green Time (sec)	25	6	11
Yellow Time (sec)	4	4	4
All-Red Time (sec)	2	2	2
Phase Time (sec)	31	12	17
Phase Split	52 %	20 %	28 %





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MOVEMENT SUMMARY

Site: Traffic Signals AM Peak Proposed Development

New T Intersection

Signals - Fixed Time Cycle Time = 60 seconds (User-Given Cycle Time)

Movem	nent Per	formance - V	ehicles								
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back o Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h
South: E	3rickmake			.,.							
2	Т	753	1.0	0.630	7.8	LOS A	13.9	98.0	0.68	0.61	40.4
3	R	9	1.0	0.024	14.3	LOS A	0.1	0.9	0.59	0.67	37.1
Approac	ch	762	1.0	0.630	7.9	LOS A	13.9	98.0	0.67	0.61	40.4
East: No	ew Link R	oad									
4	L	5	1.0	0.156	28.6	LOS C	1.3	9.5	0.86	0.73	29.4
6	R	48	1.0	0.156	28.9	LOS C	1.3	9.5	0.86	0.74	29.4
Approac	ch	54	1.0	0.156	28.9	LOS C	1.3	9.5	0.86	0.74	29.4
North: E	Brickmake	rs Drive									
7	L	79	1.0	0.348	19.5	LOS B	5.6	39.6	0.72	0.83	35.0
8	Т	198	1.0	0.348	13.0	LOS A	5.6	39.6	0.72	0.61	36.1
Approac	ch	277	1.0	0.348	14.9	LOS B	5.6	39.6	0.72	0.67	35.8
All Vehic	cles	1093	1.0	0.630	10.7	LOSA	13.9	98.0	0.70	0.63	38.4

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model used.

Moven	Movement Performance - Pedestrians											
Mov ID	Description	Demand Flow ped/h	Average Delay sec	Level of Service	Average Back Pedestrian ped	of Queue Distance m	Prop. Queued	Effective Stop Rate per ped				
P5	Across N approach	53	24.3	LOS C	0.1	0.1	0.90	0.90				
All Pede	estrians	53	24.3	LOS C			0.90	0.90				

Level of Service (LOS) Method: SIDRA Pedestrian LOS Method (Based on Average Delay) Pedestrian movement LOS values are based on average delay per pedestrian movement. Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

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PHASING SUMMARY

Site: Traffic Signals PM Peak Proposed Development

New T Intersection

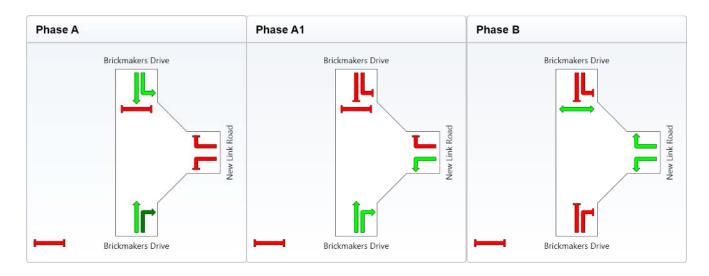
Signals - Fixed Time Cycle Time = 120 seconds (User-Given Cycle Time)

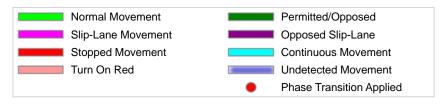
Phase times determined by the program

Sequence: Opposed Turns Input Sequence: A, A1, B Output Sequence: A, A1, B

Phase Timing Results

Phase	Α	A1	В
Green Time (sec)	85	6	11
Yellow Time (sec)	4	4	4
All-Red Time (sec)	2	2	2
Phase Time (sec)	91	12	17
Phase Split	76 %	10 %	14 %





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MOVEMENT SUMMARY

Site: Traffic Signals PM Peak Proposed Development

New T Intersection

Signals - Fixed Time Cycle Time = 120 seconds (User-Given Cycle Time)

Movement Performance - Vehicles												
Mov ID	Turn	Demand Flow veh/h	HV %	Deg. Satn v/c	Average Delay sec	Level of Service	95% Back o Vehicles veh	of Queue Distance m	Prop. Queued	Effective Stop Rate per veh	Average Speed km/h	
South: I	Brickmake	ers Drive										
2	T	256	1.0	0.163	2.7	LOS A	3.2	22.7	0.24	0.20	46.2	
3	R	11	1.0	0.055	20.1	LOS B	0.3	2.0	0.52	0.69	33.7	
Approa	ch	266	1.0	0.163	3.3	LOS A	3.2	22.7	0.25	0.22	45.6	
East: N	ew Link R	Road										
4	L	8	1.0	0.445	63.5	LOS E	4.4	31.2	0.98	0.77	19.7	
6	R	68	1.0	0.445	63.9	LOS E	4.4	31.2	0.98	0.77	19.6	
Approa	ch	77	1.0	0.445	63.8	LOS E	4.4	31.2	0.98	0.77	19.6	
North: E	Brickmake	ers Drive										
7	L	102	1.0	0.659	16.5	LOS B	28.2	199.2	0.60	0.90	36.8	
8	Т	797	1.0	0.659	10.1	LOS A	28.2	199.2	0.60	0.55	38.7	
Approac	ch	899	1.0	0.659	10.8	LOS A	28.2	199.2	0.60	0.59	38.4	
All Vehi	cles	1242	1.0	0.659	12.5	LOSA	28.2	199.2	0.54	0.52	37.5	

Level of Service (LOS) Method: Delay (RTA NSW).

Vehicle movement LOS values are based on average delay per movement

Intersection and Approach LOS values are based on average delay for all vehicle movements.

SIDRA Standard Delay Model used.

Moven	Movement Performance - Pedestrians											
Mov ID	Description	Demand Flow ped/h	Average Delay sec	Level of Service	Average Back Pedestrian ped	of Queue Distance m	Prop. Queued	Effective Stop Rate per ped				
P5	Across N approach	53	54.2	LOS E	0.2	0.2	0.95	0.95				
All Pede	estrians	53	54.2	LOS E			0.95	0.95				

Level of Service (LOS) Method: SIDRA Pedestrian LOS Method (Based on Average Delay) Pedestrian movement LOS values are based on average delay per pedestrian movement. Intersection LOS value for Pedestrians is based on average delay for all pedestrian movements.

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